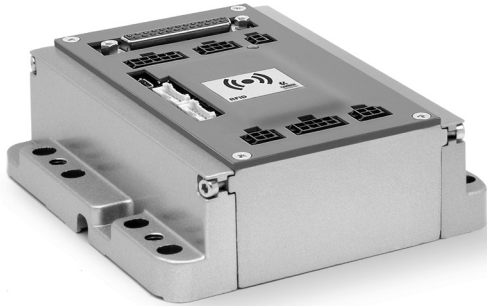


# Series DRCS drives for Stepper motors

One-size full digital drives with WLAN system and NFC integrated

SERIES DRCS DRIVES FOR STEPPER MOTORS



Series DRCS drives, compact and optimised in one size, are capable of controlling all Camozzi Stepper motors with two-phase and micro-stepping feed. The use of the micro-stepping control technology (up to 1/16 of a step) enables the drive to almost replicate a sinusoidal current while considerably reducing the natural resonance of the motor itself.

Series DRCS drives can calculate the normal resonance frequency of the motors and optimise their performance. The availability of eight inputs allows the realisation of a table of 127 commands, for each of which it is possible to set position, speed, acceleration and deceleration. Each command can be absolute or relative. Through the Step and Direction commands, it is possible to control the drive in frequency mode. The frequency defines the speed, while the number of steps defines the position. The Series DRCS drives are equipped with serial protocols CANopen CiA 301 and CiA 402 through which it is possible to perform motion control and condition monitoring of the drive. To configure the drive, wired USB 2.0 or WLAN connections can be used. Thanks to an innovative system that takes advantage of Near Field Communication (NFC) technology, it is possible to extract production and statistical data on the use of the drive, which are essential parameters for industry 4.0.

- » Full digital drive with integrated PLC functions
- » Programmable with the Camozzi QSet configuration software
- » Feedback by incremental encoder
- » NFC (Near Field Communication) system enabled
- » 127 programmable positions (setting, acceleration, speed and position)
- » Wire configuration by means of USB 2.0 and WLAN BL-BLE
- » Can be controlled in frequency (step and direction), digital I/O and serial CANopen protocol

## GENERAL DATA

|                                  |  |
|----------------------------------|--|
| <b>SUPPLY VOLTAGE</b>            |  |
| Logic                            | 18 ÷ 32 V DC   |
| Power                            | 24 ÷ 60 V DC   |
| <b>CURRENT</b>                   |  |
| Current                          | 0.1 ÷ 7 A  |
| Holding current                  | Automatic reduction of the holding current with motor in stop mode, this function can be set according to the holding current or its delay                   |
| <b>AMBIENT</b>                   |  |
| Operating temperature            | 0 ÷ 40°C (up to 55°C with forced ventilation)  |
| Storage temperature              | -20°C ÷ 70°C   |
| Humidity                         | 0 ÷ 90%  |
| Altitude                         | < 1000 meters  |
| Vibration                        | 1G (10 to 500 Hz)  |
| Protection                       | Overvoltage, minimum voltage, overtemperature, short-circuit or grounding on the motor   |
| Control method                   | 4 state PWM 20kHz  |
| Amplification type               | Dual H-Bridge, 4 Quadrants   |
| Position control encoder         | 100 to 5000 differential impulses / revolution   |
| <b>DIGITAL I/O</b>               |  |
| Input control signal             | 12 opto-isolated 24 VDC  |
| Output control signal            | 6 opto-isolated  |
| Input impulse control            | Step inlet and frequency direction maximum 10kHz   |
| Output control signal            | Electromechanical brake max current 1A   |
| <b>COMMUNICATION INTERFACE</b>   |  |
| USB                              | USB 2.0  |
| WLAN                             | BL-BLE   |
| RFID                             | with NFC devices   |
| CANopen                          | CiA 301 and CiA 402 (interpolated position mode)   |
| Microstep emulation              | High resolution by means of microstepping and a detailed synchronization.<br>Reduction of oscillations and of resonance vibrations                           |
| Anti-Resonance                   | Activation of the oscillation system in order to reduce vibrations and obtain a smooth movement, control of speed and a reduction of the time of oscillation |
| Led status                       | green led  |
| Configuration                    | Digital with the Camozzi QSet configuration software   |
| Control methods                  | Digital inputs<br>Frequency<br>CANopen   |
| <b>MEMORY</b>                    |  |
| Data retention memory            | Flash  |
| Configuration data backup memory | E <sup>2</sup> prom  |
| Weight                           | 0.46 kg  |

**CODING EXAMPLE**

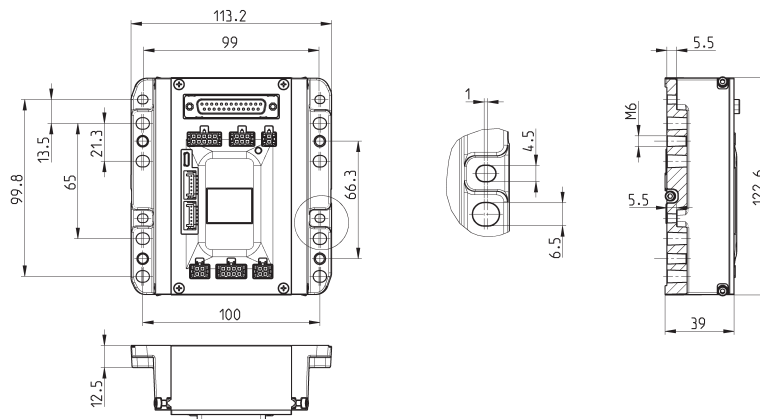
|             |          |            |          |          |          |          |          |          |          |          |
|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|----------|
| <b>DRCS</b> | <b>-</b> | <b>A05</b> | <b>-</b> | <b>8</b> | <b>-</b> | <b>D</b> | <b>-</b> | <b>0</b> | <b>-</b> | <b>A</b> |
|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|----------|

|             |   |
|-------------|---|
| <b>DRCS</b> | SERIES  |
| <b>A05</b>  | SIZE AT MAX CURRENT:<br>A05 = 7 A   |
| <b>8</b>    | SUPPLY:<br>8 = 48 V DC  |
| <b>D</b>    | COMMUNICATION:<br>D = Digital I/O and impulse frequency<br>C = CANopen, Digital I/O and impulse frequency |
| <b>0</b>    | FEEDBACK:<br>0 = Feedback   |
| <b>A</b>    | VERSIONS:<br>A = standard<br>B = WLAN BL-BLE  |

SERIES DRCS DRIVES FOR STEPPER MOTORS

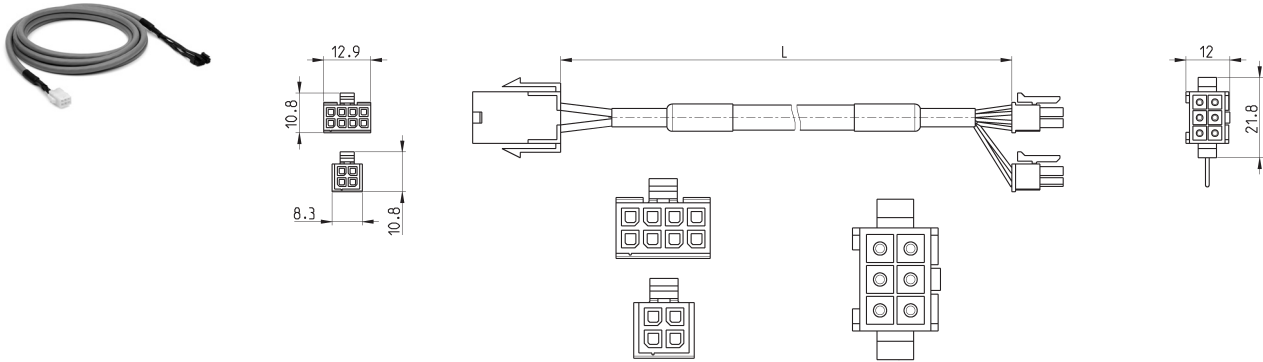
**Series DRCS drives**

For the Camozzi Stepper motors



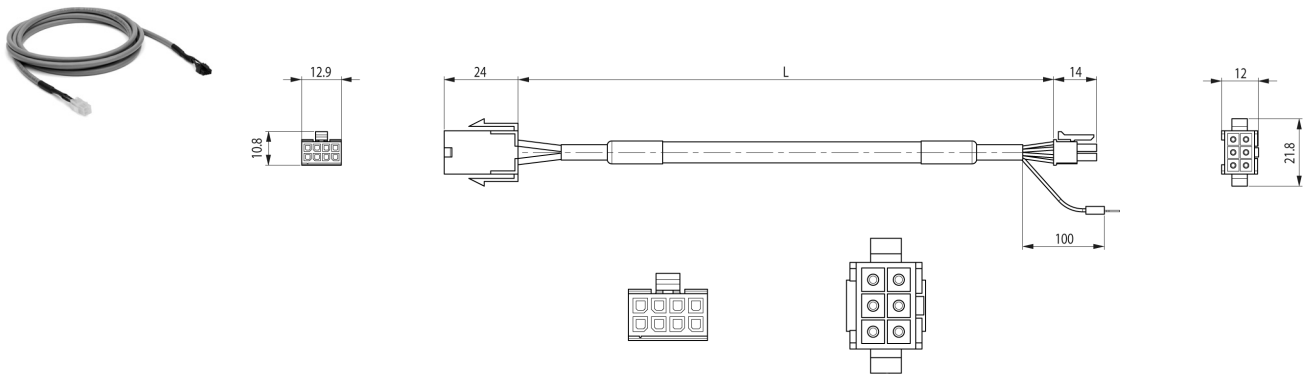
| Mod.                    | Max current | Logic supply | Power supply | Communication                              | Versions    |
|-------------------------|-------------|--------------|--------------|--|-------------|
| <b>DRCS-A05-8-D-0-A</b> | 7 A         | 24 V DC      | 24 ÷ 48 V DC | Digital I/O and impulse frequency          | standard    |
| <b>DRCS-A05-8-C-0-A</b> | 7 A         | 24 V DC      | 24 ÷ 48 V DC | CANopen, Digital I/O and impulse frequency | standard    |
| <b>DRCS-A05-8-D-0-B</b> | 7 A         | 24 V DC      | 24 ÷ 48 V DC | Digital I/O and impulse frequency          | WLAN BL-BLE |
| <b>DRCS-A05-8-C-0-B</b> | 7 A         | 24 V DC      | 24 ÷ 48 V DC | CANopen, Digital I/O and impulse frequency | WLAN BL-BLE |

### Motor cable for Series DRCS drive with brake



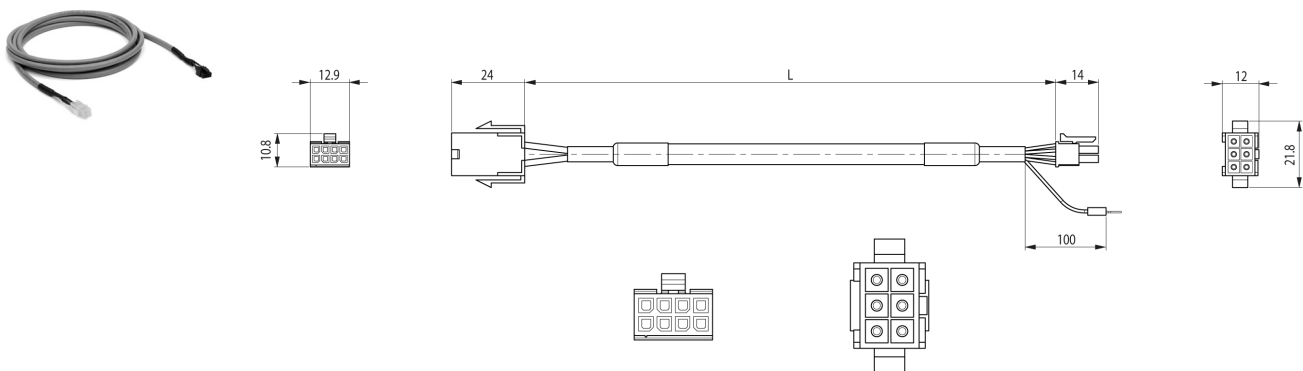
| Mod.           | Motor   | Brake | Pins | L = cable (m) |
|----------------|---------|-------|------|---------------|
| EC-210A22-B300 | Stepper | X     | 6    | 3             |
| EC-210A22-B500 | Stepper | X     | 6    | 5             |
| EC-210A22-BA00 | Stepper | X     | 6    | 10            |

### Motor cable for Series DRCS drive without brake



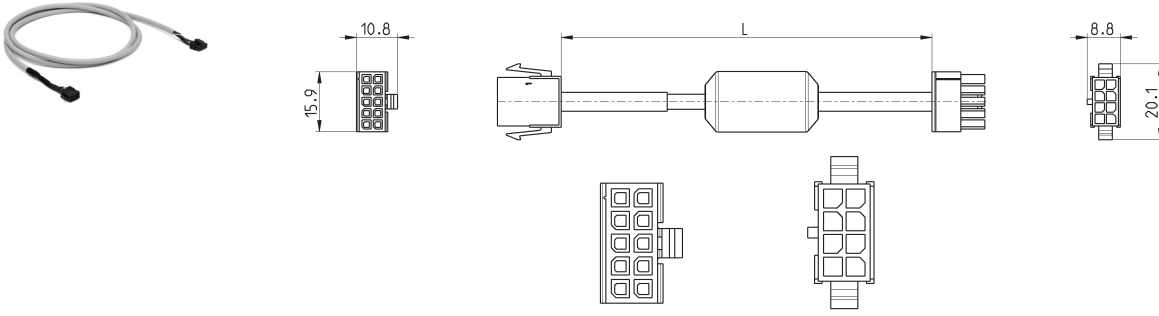
| Mod.           | Motor   | Brake | Pins | L = cable (m) |
|----------------|---------|-------|------|---------------|
| EC-200A22-B300 | Stepper | -     | 4    | 3             |
| EC-200A22-B500 | Stepper | -     | 4    | 5             |
| EC-200A22-BA00 | Stepper | -     | 4    | 10            |

### Motor cable for Series DRCS drive without brake (Nema 34 only)



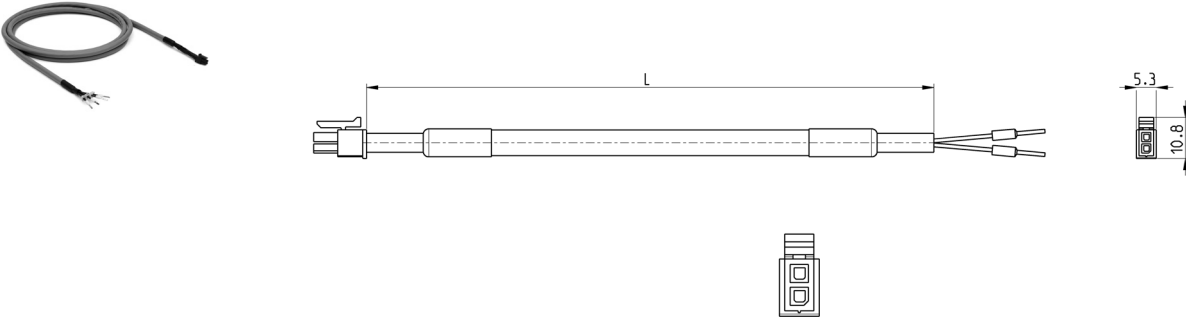
| Mod.           | Motor   | Brake | Pins | L = cable (m) |
|----------------|---------|-------|------|---------------|
| EC-200522-B300 | Stepper | -     | 5    | 3             |
| EC-200522-B500 | Stepper | -     | 5    | 5             |
| EC-200522-BA00 | Stepper | -     | 5    | 10            |

### Encoder cable for Series DRCS drive



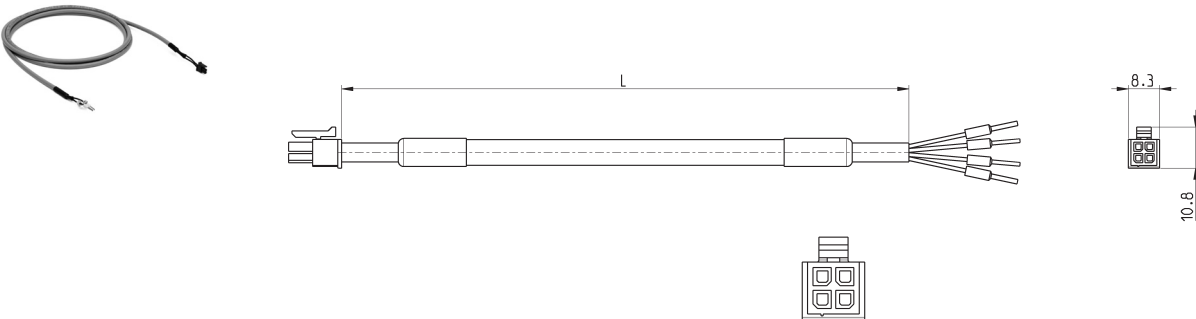
| Mod.           | Motor   | Brake | Pins | L = cable (m) |
|----------------|---------|-------|------|---------------|
| EC-220A22-B300 | Stepper | -     | 8    | 3             |
| EC-220A22-B500 | Stepper | -     | 8    | 5             |
| EC-220A22-BA00 | Stepper | -     | 8    | 10            |

### Cable for Series DRCS drive logic supply



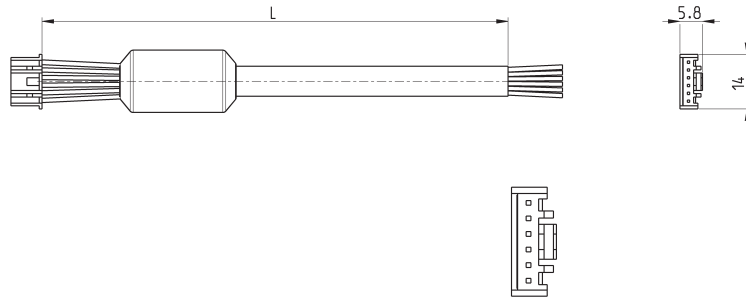
| Mod.           | Motor | Brake | Pins | L = cable (m) |
|----------------|-------|-------|------|---------------|
| EC-140222-A200 | -     | -     | 2    | 2             |

### Cable for Series DRCS drive power supply



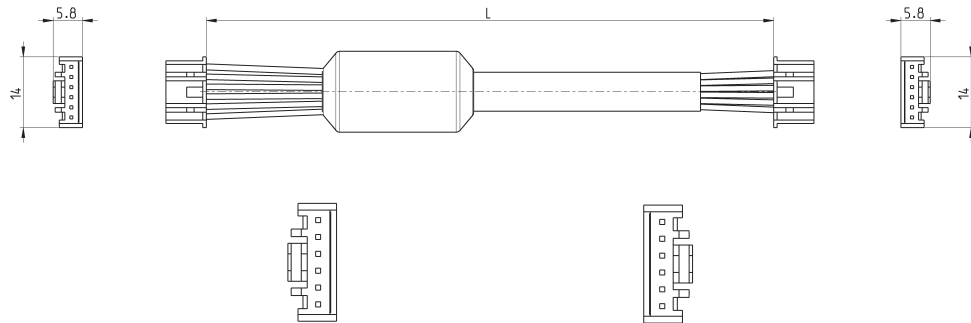
| Mod.           | Motor | Brake | Pins | L = cable (m) |
|----------------|-------|-------|------|---------------|
| EC-230422-A200 | -     | -     | 4    | 2             |

### Cable for Series DRCS drive CANopen



| Mod.           | Motor | Brake | Pins | L = cable (m) |
|----------------|-------|-------|------|---------------|
| EC-050522-A100 | -     | -     | 6    | 1             |
| EC-050522-A300 | -     | -     | 6    | 3             |
| EC-050522-A500 | -     | -     | 6    | 5             |

### Cable for Series DRCS drive CANopen expansion



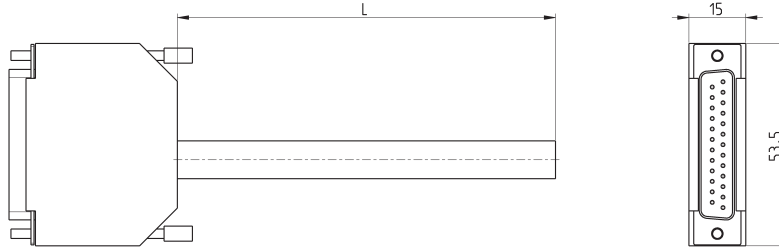
| Mod.            | Motor | Brake | Pins | L = cable (m) |
|-----------------|-------|-------|------|---------------|
| EC-0130422-A030 | -     | -     | 6    | 0.3           |

### CAN terminating resistor for Series DRCS drives



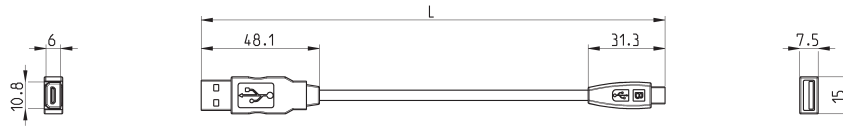
| Mod.      | Motor | Brake | Pins | L = cable (m) |
|-----------|-------|-------|------|---------------|
| EC-060623 | -     | -     | 6    | -             |

### Multipole I/O cable 25P M



| Mod.  | Motor | Brake | Pins | L = cable (m) |
|-------|-------|-------|------|---------------|
| G2W-1 | -     | -     | 25   | 1             |
| G2W-3 | -     | -     | 25   | 3             |

### USB to Micro USB cable Mod. G11W-G12W-2



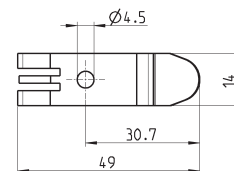
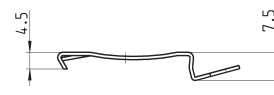
| Mod.        | description                 | connections               | material for outer sheath | cable length "L" (m) |
|-------------|-----------------------------|---------------------------|---------------------------|----------------------|
| G11W-G12W-2 | black shielded cable 28 AWG | standard USB to Micro USB | PVC                       | 2                    |

### Mounting brackets for DIN rail



DIN EN 50022 (mm 7,5 x 35 - width 1)

Supplied with:  
2x plates  
2x screws M4x6 UNI 5931



|          |
|----------|
| Mod.     |
| PCF-E520 |